

الاسم:
الرقم:

مسابقة في مادة الفيزياء
المدة: ساعة ونصف

This exam is formed of three obligatory exercises in three pages.
The use of non-programmable calculator is recommended.

Exercise 1 (7 pts)

Mechanical oscillations

A mechanical oscillator consists of a block (S) of mass $m = 50 \text{ g}$ and a massless spring of force constant k . The horizontal spring is fixed from one of its ends to a fixed support A. (S) is attached to the other end of the spring and can move without friction on a horizontal surface (Doc. 1).

At equilibrium, the center of mass G of (S) coincides with the origin O of the x-axis.

(S) is shifted from its equilibrium position by a displacement x_0 and then it is released without initial velocity at an instant $t_0 = 0$. (S) then performs mechanical oscillations.

At an instant t , the abscissa of G is $x = \overline{OG}$ and the algebraic value of its velocity is $v = x' = \frac{dx}{dt}$.

The aim of this exercise is to determine the maximum speed attained by G.

Take:

- the horizontal plane containing G as the reference level for gravitational potential energy;
- $\pi^2 = 10$.

- 1) The mechanical energy ME of the system (Oscillator - Earth) is conserved. Why?
- 2) Write the expression of ME in terms of m , v , k and x .
- 3) Determine the second order differential equation in x that governs the motion of G.
- 4) Deduce, in terms of m and k , the expression of the proper (natural) period T_0 of the oscillations.
- 5) An appropriate device shows x as a function of time (Doc. 2).

5.1) Referring to document 2, indicate

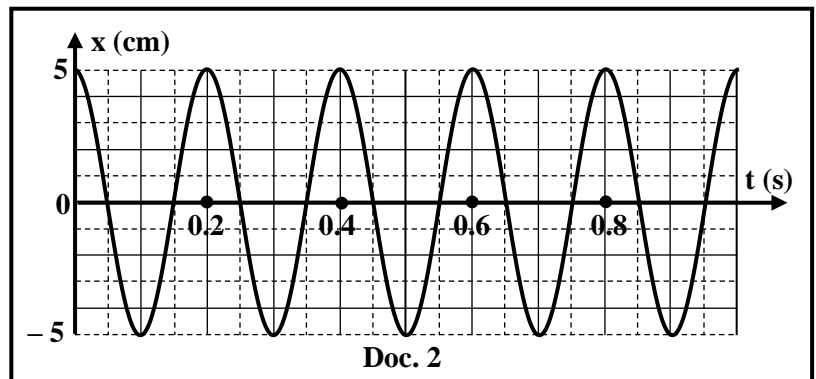
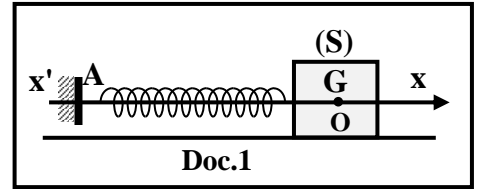
the values of T_0 and x_0 .

5.2) Deduce the value of k .

5.3) Prove that the mechanical energy of the system (Oscillator - Earth) is $ME = 6.25 \times 10^{-2} \text{ J}$.

5.4) Using document 2, indicate an instant at which the elastic potential energy of the spring is zero.

5.5) Determine the maximum speed attained by G.



Exercise 2 (6 pts)

Studying the motion of an object

Consider:

- a rail AOB located in a vertical plane composed of two straight parts: a horizontal part AO and an inclined part OB making an angle $\alpha = 30^\circ$ with the horizontal;
- two objects (S_1) and (S_2) taken as particles of same mass $m = 80$ g;
- a massless spring (R), of force constant $k = 200$ N/m and natural length ℓ_0 , fixed from one of its ends to a support at A with the other end free.

Take:

- the horizontal plane containing O as the reference level for gravitational potential energy;
- $g = 10$ m/s².

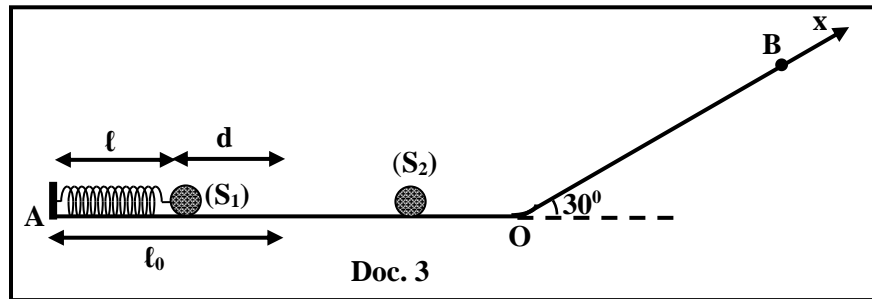
1) Launching particle (S_1)

In order to launch (S_1), it is placed against the free end of the spring, the spring is compressed by a distance d , and then the system [Spring - (S_1)] is released from rest (Doc.3).

When the spring returns to its natural length ℓ_0 , (S_1) leaves the spring with a velocity \vec{V}_1 parallel to AO. After launching, (S_1) moving with the velocity \vec{V}_1 , collides head-on with (S_2) which is placed initially at rest on the rail AO.

Just after the collision, (S_1) stops and (S_2) moves with a velocity \vec{V}_2 parallel to AO and of magnitude $V_2 = 5$ m/s.

(S_1) and (S_2) move without friction on the rail AO.



1.1) Apply the law of conservation of linear momentum to show that the magnitude of \vec{V}_1 is $V_1 = 5$ m/s.

1.2) Deduce that the collision between (S_1) and (S_2) is elastic.

1.3) Determine the value of d .

2) Motion of (S_2) on the inclined part OB

At the instant $t_0 = 0$, (S_2) starts from O on the inclined part OB with a velocity $\vec{V}_0 = V_0 \hat{i} = 5 \hat{i}$ (m/s), where \hat{i} is the unit vector along the x-axis parallel to OB. On this part, (S_2) is submitted to a friction force \vec{f} of constant magnitude f and of direction opposite to its motion.

2.1) Name the external forces acting on (S_2) during its motion along the track OB.

2.2) Show that the sum of the external forces acting on (S_2) during its upward motion along OB is:

$$\Sigma \vec{F} = -(f + mgsin\alpha) \hat{i}.$$

2.3) The expression of the linear momentum of (S_2) during its upward motion along OB is:

$$\vec{P} = (-0.9t + 0.4) \hat{i} \text{ (SI)}.$$

Knowing that $\frac{d\vec{P}}{dt} = \Sigma \vec{F}$, determine f .

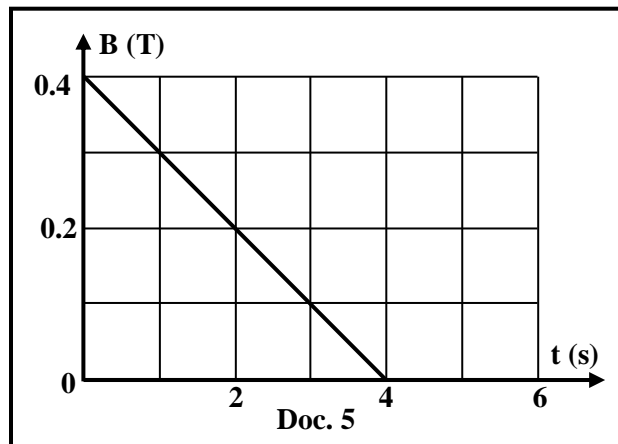
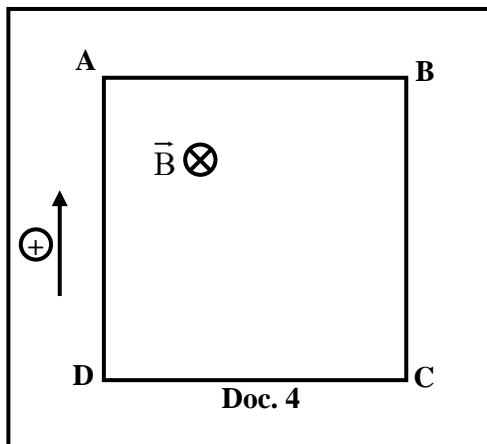
Exercise 3 (7 pts)

Electromagnetic induction

The aim of this exercise is to determine the direction of the induced current in a square-shaped loop by two methods.

For this aim, consider a square-shaped loop ABCD, of side $a = 10 \text{ cm}$ and resistance $r = 2 \Omega$, is placed in a uniform magnetic field \vec{B} , whose magnitude varies with time. The direction of \vec{B} is perpendicular to the plane of the loop (Doc. 4).

Document 5 shows, during the time interval $[0, 4 \text{ s}]$, the magnitude B of \vec{B} as a function of time.



- 1) An induced current flows in the loop during the time interval $[0, 4 \text{ s}]$. Justify.
- 2) Apply Lenz's law to specify the direction of the induced current in the loop.
- 3) Prove that the expression of B during the time interval $[0, 4 \text{ s}]$ is: $B = -0.1t + 0.4 \text{ (SI)}$.
- 4) Take into consideration the chosen positive direction indicated on document 4, determine, as a function of time, the expression of the magnetic flux crossing the loop.
- 5) Deduce the value of the induced electromotive force « e ».
- 6) The induced current in the loop is given by $i = \frac{e}{r}$. Deduce the value and the direction of i .
- 7) Compare the direction of the induced current obtained in part 6 with that obtained in part 2.

Exercise 1 (7 pts)

Mechanical oscillations

Part	Answer	Mark
1	Friction is negligible, then the mechanical energy of the system is conserved. (Or the sum of the works done by the non-conservative forces is zero, then the mechanical energy is conserved).	0.25
2	$ME = KE + EPE = \frac{1}{2} m v^2 + \frac{1}{2} k x^2$	0.5
3	$ME = \text{constant}$, then $\frac{dME}{dt} = 0$, so $m v v' + k x x' = 0$, hence $v (m x'' + k x) = 0$ $v = 0$ is rejected , then $x'' + \frac{k}{m} x = 0$	1
4	The differential equation is of the form: $x'' + \omega_0^2 x = 0$, with $\omega_0 = \sqrt{\frac{k}{m}}$ $T_0 = \frac{2\pi}{\omega_0}$; therefore, $T_0 = 2\pi \sqrt{\frac{m}{k}}$	1.5
5	5.1 $T_0 = 0.2 \text{ s}$ and $x_0 = 5 \text{ cm}$	1
	5.2 $0.2 = 2\pi \sqrt{\frac{0.05}{k}}$ $k = 50 \text{ N/m}$	1
	5.3 When the speed is zero, the elongation is maximum, then: $ME = KE + EPE = 0 + EPE = \frac{1}{2} k X_{\text{max}}^2$ $ME = 0.5 \times 50 \times 0.05^2 = 0.0625 \text{ J} = 6.25 \times 10^{-2} \text{ J}$	0.75
	5.4 $t = 0.05 \text{ s}$ or $t = 0.15 \text{ s}$ or $t = 0.25 \text{ s}$	0.25
	5.5 When G passes through O, its speed is maximum. Then: $ME = KE + EPE = KE + 0 = \frac{1}{2} m V_{\text{max}}^2$ $0.0625 = 0.5 \times 0.05 \times (V)_{\text{max}}^2$; therefore, $V_{\text{max}} = 1.58 \text{ m/s}$	0.75

Exercise 2 (6 pts)

Study the motion of an object

Part	Answer	Mark
1	<p>1.1</p> $\vec{P}_{J.B.C} = \vec{P}_{J.A.C}$ $m\vec{V}_1 + \vec{0} = \vec{0} + m\vec{V}_2, \vec{V}_1 = \vec{V}_2$ <p>then, $V_1 = 5 \text{ m/s}$</p>	1.5
	<p>1.2</p> <p>System $[(S_1), (S_2)]$ The collision is elastic if $KE_{\text{system}(\text{before})} = KE_{\text{system}(\text{after})}$ $KE_{(\text{before})} = KE_{(S_1)} + KE_{(S_2)} = \frac{1}{2}mV_1^2 + 0 = \frac{1}{2} \times 0.08 \times 5^2 + 0 = 1 \text{ J}$ $KE_{(\text{after})} = KE_{(S_1)} + KE_{(S_2)} = 0 + \frac{1}{2}mV_2^2 = 0 + \frac{1}{2} \times 0.08 \times 5^2 = 1 \text{ J}$ Therefore, the collision is elastic.</p>	1
	<p>1.3</p> <p>Apply the law of conservation of mechanical energy of the system [Oscillator-Earth] $ME_{(R)}$ is compressed by $d = ME_{(R)}$ is in its initial length, $(KE + GPE + EPE)_{(R)}$ is compressed by $d = (KE + GPE + EPE)_{(R)}$ is in its initial length $0 + \frac{1}{2}kd^2 + 0 = \frac{1}{2}mV_1^2 + 0 + 0,$ $\frac{1}{2} \times 200 \times d^2 = \frac{1}{2} \times 0.08 \times 5^2$ then $d = 0.1 \text{ m} = 10 \text{ cm}$</p>	1.5
2	<p>2.1</p> <p>The forces acting on (S_2) on OB are: $m\vec{g}$: its weight, \vec{N}: Normal reaction \vec{f}: friction</p>	0.75
	<p>2.2</p> $\Sigma \vec{F} = m\vec{g} + \vec{N} + \vec{f},$ <p>Component along the direction \vec{Ox}: $\Sigma \vec{F} = -mgsin\alpha \vec{i} + 0 \vec{i} - f \vec{i}$ $\Sigma \vec{F} = -(f + mgsin\alpha)\vec{i}$</p> <p>Or : $\Sigma \vec{F} = m\vec{g} + \vec{N} + \vec{f} = -mg \sin\alpha \vec{i} + mg \cos\alpha \vec{j} - N \vec{j} - f \vec{i}$ But : $mg \cos\alpha \vec{j} - N \vec{j} = 0$, then, $\Sigma \vec{F} = -(f + mgsin\alpha)\vec{i}$</p>	0.75
	<p>2.3</p> $\frac{d\vec{P}}{dt} = \Sigma \vec{F},$ $-0.9 \vec{i} = -(f + mgsin\alpha)\vec{i}$ $-0.9 = -f - 0.08 \times 10 \times 0.5$ <p>Therefore, $f = 0.5 \text{ N}$</p>	0.5

Exercise 3 (7 pts)

Electromagnetic induction

Part	Answer	Mark
1	During the interval [0 s, 4 s], B varies with time, then the magnetic flux varies with time, therefore an emf (e) is induced in the circuit. The circuit is closed, then a current is induced in the circuit.	1
2	During the interval [0 s, 4 s], B decreases with time, then the direction of the induced magnetic field as that of \vec{B} to oppose this decrease (Lenz's law). Using the right hand rule, the induced current flows in the loop in the positive direction (clockwise).	1
3	In the interval [0s, 4s], B(t) varies linearly with time : $B = at + b$ $a = \text{slope} = \frac{0 - 0.4}{4 - 0} = -0.1 \text{ T/s}$ $0 = -0.1 \times 4 + b \quad b = 0.4 \text{ T}$ then $B = -0.1t + 0.4$	1
4	$\phi = BS \cos(\vec{B}, \vec{n}) = (-0.1t + 0.4) \times (0.1)^2 \times \cos(0)$ $\phi = -10^{-3} t + 4 \times 10^{-3} \quad (\text{SI})$	1
5	$e = -\frac{d\phi}{dt} = 10^{-3} \text{ V}$	1
6	$i = \frac{e}{r} = \frac{10^{-3}}{2} = 0.5 \times 10^{-3} \text{ A}$ $i > 0$, then the induced current flows in the positive direction (clockwise).	1.5
7	They are the same.	0.5